

Geometry of Tangential and Configuration Chain Complexes for Higher Weights

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Abstract. In this study, the geometry of a first order tangent group and of configuration chain complexes is proposed. First, the morphisms are introduced to define the geometry for weight $n = 4$, and then this geometry is extended for higher weight $n = 5$. All associated commutative diagrams are presented.

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1. INTRODUCTION

Researchers have often used configuration spaces and its chain complex as a tool in active areas of pure mathematics. In the Grassmannian configuration chain complex, for example, free abelian groups are connected through two types of differential boundary maps d and p [22]. Configuration spaces are naturally related to polylogarithmic groups and its chain complexes; that is why many researchers have tried to find the relationship between configurations and polylogarithmic group chain complexes.

Bloch [1] defined polylogarithmic group $\mathcal{B}(F)$ for weight 1; it is a quotient of \mathbb{Z} -module $\mathbb{Z}[F^\bullet]$ and Abel's five terms relation. For weight 2, Bloch [1] defined a group denoted by $\mathcal{B}_2(F)$, generated by the cross ratio of four points, and introduced a chain complex called Bloch-Suslin complex.

$$\mathcal{B}_2(F) \xrightarrow{\delta} \wedge^2 F^\times$$

Goncharov introduced the concept of triple cross ratio to define the group $\mathcal{B}_3(F)$ for weight 3. He further generalized the Bloch group as $\mathcal{B}_n(F)$ creating a generalized version of the

Bloch-Suslin complex that was called the Goncharov Complex

$$\mathcal{B}_n(F) \xrightarrow{\delta_n} \mathcal{B}_{n-1}(F) \otimes F^\times \xrightarrow{\delta_{n-1}} \dots \xrightarrow{\delta_2} \mathcal{B}_2(F) \otimes \wedge^{n-2}(F) \xrightarrow{\delta_1} \wedge^n(F^\times)$$

First, Goncharov found geometry between configuration and Bloch-Suslin polylogarithmic chain complex through homomorphisms for weight 2 and proved the commutativity of the associated diagram [7]. Goncharov also extended his work to define the geometry of configuration and the generalized polylogarithmic chain complex called Goncharov complex for weight 3 [7]. On the other hand, Khalid et al. [12–15, 17–19] introduced the generalized geometry between Goncharov polylogarithmic complex and configuration chain complex for any weight n .

Later, Cathelineau introduced variant of Goncharov complex called Cathelineau complex in two different ways: one was infinitesimal while other was in a tangential setting [2, 3]. $\beta_n(F)$ was the group for infinitesimal chain complex and $T\mathcal{B}_n(F)$ for tangential complex. Cathelineau first introduced the Tangent to Bloch-Suslin complex $T\mathcal{B}_2(F) \rightarrow F \otimes F^\times \oplus \wedge^2 F^\times$ and then generalized the former.

$$T\mathcal{B}_n(F) \xrightarrow{\delta_{n,\varepsilon}} \dots \xrightarrow{\delta_{1,\varepsilon}} \frac{T\mathcal{B}_2(F) \otimes \wedge^{n-2} F^\times}{F \otimes \mathcal{B}_2(F) \otimes \wedge^{n-3} F^\times} \xrightarrow{\delta_\varepsilon} (F \otimes \wedge^{n-1} F^\times) \oplus (\wedge^n F)$$

Siddiqui introduced both the cross ratio of four points and the famous Siegel's cross-ratio properties in tangential form and also showed that the Goncharovs projected five term relation can also be defined for tangent group $T\mathcal{B}_2(F)$ [20]. With the help these constructions, Siddiqui [20] defined the morphisms to connect the configuration sub complex and first order tangential chain complex for both weight 2 and 3, in order to come up with commutative diagrams [20].

Hussain [11] introduced second and third order tangent groups denoted by $T\mathcal{B}_2^2(F)$ and $T\mathcal{B}_3^2(F)$ for weight 2 and 3. Hussain [11] also found the relation of these groups with configuration chain complexes through morphisms and proved the commutativity of the associated diagrams.

Here in this article, some interesting morphisms are introduced to define the new geometry of configuration and tangential chain complexes for higher weights 4 and 5. Section 2 describes the basic concepts of configuration chain complexes, truncated polynomial ring, cross ratio in dual numbers, classical polylogarithmic groups complexes, first order tangent group and generalized tangential groups chain complex, geometry between configuration, and the tangential complexes for weight 2 and 3. Section 3 provides the geometry and commutative diagrams of the configuration and tangential complexes for weight 4 and 5. The last section concludes the entire research work.

2. PRELIMINARIES AND BASIC CONCEPTS

2.1. Grassmannian Configuration Chain Complex. Let us have $GL_n(F)$ be a general linear group of order n , acting diagonally on a set V^n . The elements of group action $GL_n(F) * V^n = V^n$ are (v_0, \dots, v_n) called configurations of n vectors in n -dimensional vector space V defined some arbitrary field F .

Consider a free abelian group $G_n(V)$ generated by all possible projective configuration of

n points $(v_1, \dots, v_n) \in V^n$. Let d be a differential boundary morphism, defined as

$$d : (v_0, \dots, v_n) = \sum_{i=0}^n (-1)^i (v_0, \dots, \hat{v}_i, \dots, v_n) \quad (2.1)$$

Another differential map p is defined as

$$p : (v_0, \dots, v_n) = \sum_{i=0}^n (-1)^i (v_i | v_0, \dots, \hat{v}_i, \dots, v_n) \quad (2.2)$$

Suslin [22] connected above free abelian groups using above two differential morphisms in following way to define Grassmannian configuration chain complex

$$\begin{array}{ccccccc} & & \vdots & & \vdots & & \vdots \\ & & \downarrow p & & \downarrow p & & \downarrow p \\ \dots & \xrightarrow{d} & G_m(n) & \xrightarrow{d} & G_{m-1}(n) & \xrightarrow{d} & G_{m-2}(n) \\ & & \downarrow p & & \downarrow p & & \downarrow p \\ \dots & \xrightarrow{d} & G_{m-1}(n-1) & \xrightarrow{d} & G_{m-2}(n-1) & \xrightarrow{d} & G_{m-3}(n-1) \\ & & \downarrow p & & \downarrow p & & \downarrow p \\ \dots & \xrightarrow{d} & G_{m-2}(n-2) & \xrightarrow{d} & G_{m-3}(n-2) & \xrightarrow{d} & G_{m-4}(n-2) \end{array} \quad (A)$$

The above diagram is bi-complex and each square is commutative (see [16, 22]).

2.2. Tangential Configuration Spaces. Assume that F be a field with 0 characteristic, we define the ring of k^{th} truncated polynomial by $F[\varepsilon]_k := F[\varepsilon]/\varepsilon^k, k \geq 1$. Now define an affine space $\mathbb{A}_{F[\varepsilon]_n}^n$ defined over truncated polynomial $F[\varepsilon]_n$. Assume $v = (a_1, a_2, a_3, \dots, a_n)^t \in \mathbb{A}_F^n \setminus (0, 0, 0, \dots, 0)^t$ and $v_\varepsilon = (a_{1,\varepsilon}, a_{2,\varepsilon}, a_{3,\varepsilon}, \dots, a_{n,\varepsilon})^t \in \mathbb{A}_F^n$ also $v_{\varepsilon^n} = (a_{1,\varepsilon^{k-1}}, a_{2,\varepsilon^{k-1}}, a_{3,\varepsilon^{k-1}}, \dots, a_{n,\varepsilon^{k-1}})^t \in \mathbb{A}_F^n$ [11].

Let $G_m(\mathbb{A}_{F[\varepsilon]_k}^n)$ be a free abelian group generated by $(v_1^*, v_2^*, v_3^*, \dots, v_m^*)$ m vectors in affine space $(\mathbb{A}_{F[\varepsilon]_k}^n)$ [11], where the element $v^* = v + v_\varepsilon \varepsilon + \dots + v_{\varepsilon^{k-1}} \varepsilon^{k-1}$. Now define the a boundary map

$$d : G_m(\mathbb{A}_{F[\varepsilon]_k}^n) \rightarrow G_{m-1}(\mathbb{A}_{F[\varepsilon]_k}^n)$$

and another differential map

$$p : G_m(\mathbb{A}_{F[\varepsilon]_k}^n) \rightarrow G_{m-1}(\mathbb{A}_{F[\varepsilon]_k}^{n-1})$$

with the help of these maps following is Grassmannian tangential configuration chain complex

$$\begin{array}{ccccccc} G_m(\mathbb{A}_{F[\varepsilon]_k}^n) & \xrightarrow{d} & G_{m-1}(\mathbb{A}_{F[\varepsilon]_k}^n) & \xrightarrow{d} & G_{m-2}(\mathbb{A}_{F[\varepsilon]_k}^n) & & \\ \downarrow p & & \downarrow p & & \downarrow p & & \\ G_{m-1}(\mathbb{A}_{F[\varepsilon]_k}^{n-1}) & \xrightarrow{d} & G_{m-2}(\mathbb{A}_{F[\varepsilon]_k}^{n-1}) & \xrightarrow{d} & G_{m-3}(\mathbb{A}_{F[\varepsilon]_k}^{n-1}) & & \end{array} \quad (B)$$

2.3. Cross Ratio. Let us define the cross ratio of 4 points as

$$r(v_0, v_1, v_2, v_3) = \frac{\Delta(v_0, v_3)\Delta(v_1, v_2)}{\Delta(v_0, v_2)\Delta(v_1, v_3)}$$

where $(v_0, v_1, v_2, v_3) \in A_F^2$ or \mathbf{P}_F^1 . Siegel [21] defined the following most important property of ratio

$$1 = \frac{\Delta(v_0, v_3)\Delta(v_1, v_2)}{\Delta(v_0, v_2)\Delta(v_1, v_3)} + \frac{\Delta(v_0, v_1)\Delta(v_2, v_3)}{\Delta(v_0, v_2)\Delta(v_1, v_3)}. \quad (2.3)$$

Or

$$\frac{\Delta(v_0, v_2)\Delta(v_1, v_3) - \Delta(v_0, v_3)\Delta(v_1, v_2)}{\Delta(v_0, v_2)\Delta(v_1, v_3)} = \frac{\Delta(v_0, v_1)\Delta(v_2, v_3)}{\Delta(v_0, v_2)\Delta(v_1, v_3)}. \quad (2.4)$$

2.3.1. Cross Ratio in $F[\varepsilon]_k$. First we consider the following cases

a : For $n=2$ and $k=1$,

$$\Delta(v_1^*, v_2^*) = \Delta(v_1^*, v_2^*)_{\varepsilon^0} = \Delta(v_1, v_2)$$

b : For $n=2$ and $k=2$,

$$\Delta(v_1^*, v_2^*) = \Delta(v_1^*, v_2^*)_{\varepsilon^0} + \Delta(v_1^*, v_2^*)_{\varepsilon^1}\varepsilon$$

$$\text{where } \Delta(v_1^*, v_2^*)_{\varepsilon^1} = \Delta(v_1, v_{2,\varepsilon}) + \Delta(v_{1,\varepsilon}, v_2)$$

c : For $n=2$ and $k=3$,

$$\Delta(v_1^*, v_2^*) = \Delta(v_1^*, v_2^*)_{\varepsilon^0} + \Delta(v_1^*, v_2^*)_{\varepsilon^1}\varepsilon + \Delta(v_1^*, v_2^*)_{\varepsilon^2}\varepsilon^2$$

$$\text{where } \Delta(v_1^*, v_2^*)_{\varepsilon^2} = \Delta(v_1, v_{2,\varepsilon^2}) + \Delta(v_{1,\varepsilon}, v_{2,\varepsilon}) + \Delta(v_{1,\varepsilon^2}, v_2).$$

Following is cross ratios in $F[\varepsilon]_k$ [11]

$$\mathbf{r}(v_0^*, v_1^*, v_2^*, v_3^*) = (r_{\varepsilon^0} + r_{\varepsilon^1}\varepsilon + \dots + r_{\varepsilon^{k-1}}\varepsilon^{k-1})(v_0^*, v_1^*, v_2^*, v_3^*)$$

Where

$$r_{\varepsilon^0}(v_0^*, v_1^*, v_2^*, v_3^*) = r(v_0, v_1, v_2, v_3) = \frac{\Delta(v_0, v_3)\Delta(v_1, v_2)}{\Delta(v_0, v_2)\Delta(v_1, v_3)}, \quad (2.5)$$

$$r_{\varepsilon^1}(v_0^*, v_1^*, v_2^*, v_3^*) = \frac{\{\Delta(v_0^*, v_3^*)\Delta(v_1^*, v_2^*)\}_{\varepsilon}}{\Delta(v_0, v_2)\Delta(v_1, v_3)} - r(v_0, v_1, v_2, v_3) \frac{\{\Delta(v_0^*, v_2^*)\Delta(v_1^*, v_3^*)\}_{\varepsilon}}{\Delta(v_0, v_2)\Delta(v_1, v_3)} \quad (2.6)$$

$$\begin{aligned} r_{\varepsilon^2}(v_0^*, v_1^*, v_2^*, v_3^*) &= \frac{\{\Delta(v_0^*, v_3^*)\Delta(v_1^*, v_2^*)\}_{\varepsilon}}{\Delta(v_0, v_2)\Delta(v_1, v_3)} - r(v_0^*, v_1^*, v_2^*, v_3^*) \frac{\{\Delta(v_0^*, v_2^*)\Delta(v_1^*, v_3^*)\}_{\varepsilon}}{\Delta(v_0, v_2)\Delta(v_1, v_3)} \\ &\quad - r(v_0, v_1, v_2, v_3) \frac{\{\Delta(v_0^*, v_2^*)\Delta(v_1^*, v_3^*)\}_{\varepsilon}}{\Delta(v_0, v_2)\Delta(v_1, v_3)} \end{aligned} \quad (2.7)$$

and so on

2.4. Classical Polylog Chain Complexes. The p -logarithm function is a series defined as $Li_p(z) = \sum_{n=0}^{\infty} \frac{z^n}{n^p}$, $z \leq 1$, with property $\log(a) + \log(b) - \log(ab) = 0$. Assume that $Z[\mathbf{P}_F^1/\{0, 1, \infty\}]$ is a free abelian group generated by a symbol $[x]$ where symbol $[x]$ means logarithms of x [5].

Definition 2.5. $\mathcal{B}(F)$ is a Scissor congruence group defined as $Z[\mathbf{P}_F^1/\{0, 1, \infty\}]$ is quotient by expression called Abel five terms relation $[x] - [y] + \left[\frac{y}{x}\right] - \left[\frac{1-y^{-1}}{1-x^{-1}}\right] + \left[\frac{1-y}{1-x}\right]$, $x \neq y$ and $x, y \neq 0, 1$

2.5.1. Bloch Group for Weight-1. Bloch [1] defined $\mathcal{R}_1(F) \subset Z[\mathbf{P}_F^1/\{0, 1, \infty\}]$, generated by the relation $\{xy\} - \{x\} - \{y\}$, $(x, y \in F^\times)$. Then $\mathcal{B}_1(F) \subset Z[\mathbf{P}_F^1/\{0, 1, \infty\}]$ is called Bloch group for weight 1 defined as $\mathcal{B}_1(F) = Z[\mathbf{P}_F^1/\{0, 1, \infty\}]/\langle \mathcal{R}_1(F) \rangle$. He defined a map $\delta_1 : \mathcal{B}_1(F) \rightarrow F^\times$, defined as $\delta_1 : [x] \rightarrow x$. This map is also an isomorphism. So, $\mathcal{B}_1(F) \cong F^\times$.

2.5.2. Bloch-Suslin Chain Complex. Let $\mathcal{R}_2(F) \subset Z[\mathbf{P}_F^1/\{0, 1, \infty\}]$ is a sub group generated by the relation $\sum_{i=0}^4 (-1)^i r(v_0, \dots, \hat{v}_i, \dots, v_4)$, define a morphism $\delta_2 : Z[\mathbf{P}_F^1/\{0, 1, \infty\}] \rightarrow \wedge^2 F^\times$, where $\delta_2 : [x] \rightarrow (1-x) \wedge x$. This helped to defined a dilogarithm Bloch group for weight 2 as $\mathcal{B}_2(F) = Z[\mathbf{P}_F^1/\{0, 1, \infty\}]/\langle \mathcal{R}_2(F) \rangle$ which connected $\mathcal{B}_2(F)$ with $\wedge^2 F^\times$ to form a chain complex called the Bloch-Suslin complex [1, 10].

$$\mathcal{B}_2(F) \xrightarrow{\delta} \wedge^2 F^\times$$

where δ is an induced map defined as

$$\delta : [v]_2 \rightarrow (1-v) \wedge v$$

2.5.3. Goncharov Chain Complex for Weight-3. Goncharov [6,7] defined $\mathcal{R}_3(F) \subset Z[\mathbf{P}_F^1/\{0, 1, \infty\}]$, such that

$$\mathcal{R}_3(F) = \sum_{i=0}^6 (-1)^i Alt_6 \left[\begin{array}{c} (v_0, v_1, v_3)(v_1, v_2, v_4)(v_0, v_2, v_5) \\ (v_0, v_1, v_4)(v_1, v_2, v_5)(v_0, v_2, v_3) \end{array} \right] \quad (2.8)$$

For weight 3 Goncharov [7-9] introduced a group $\mathcal{B}_3(F) = Z[\mathbf{P}_F^1/\{0, 1, \infty\}]/\langle \mathcal{R}_3(F) \rangle$. Chain complex for weight 3 is given by

$$\mathcal{B}_3(F) \xrightarrow{\delta} \mathcal{B}_2(F) \otimes F^\times \xrightarrow{\delta} \wedge^3 F^\times$$

where

$$\delta : [v]_3 \rightarrow [v]_2 \otimes v$$

Lemma 2.6. $\delta \circ \delta = 0$ (see [7])

2.6.1. *Weight- n .* Goncharov [7] generalized $\mathcal{B}(F)$ as $\mathcal{B}_n(F) = Z[\mathbf{P}_F^1/\{0, 1, \infty\}]/\langle R_n(F) \rangle$, where $R_n(F) \subset Z[\mathbf{P}_F^1]$ is the kernel of the map $\delta_n : Z[\mathbf{P}_F^1/\{0, 1, \infty\}] \rightarrow \mathcal{B}_{n-1}(F) \otimes F^\times$. Then Goncharov generalized Bloch-Suslin complex for any weight n , called Goncharov complex

$$\mathcal{B}_n(F) \xrightarrow{\delta_n} \mathcal{B}_{n-1}(F) \otimes F^\times \xrightarrow{\delta_{n-1}} \mathcal{B}_{n-2}(F) \otimes \wedge^2(F) \xrightarrow{\delta_{n-2}} \dots \xrightarrow{\delta_2} \mathcal{B}_2(F) \otimes \wedge^{n-2}(F) \xrightarrow{\delta_1} \wedge^n(F^\times) \quad (2.9)$$

Lemma 2.7. $\delta_{n-1} \circ \delta_n = 0$ (see [7, 17])

2.8. Tangent Groups and Generalized Tangent Complexes.

2.8.1. *First Order Tangent Group.* For any elements $x, x' \in F$ and $\langle x; x' \rangle_2 = [x + x' \varepsilon] - [x] \in \mathbb{Z}[F[\varepsilon]_2]$, Cathelineau [4] introduced $T\mathcal{B}_2(F)$ as a first order tangent group. It is a \mathbb{Z} -module generated by the elements $\langle x; x' \rangle_2 \in \mathbb{Z}[F[\varepsilon]_2]$ an quotient by the five term relation

$$\langle x; x' \rangle - \langle y; y' \rangle + \left\langle \frac{y}{x}; \left(\frac{y}{x}\right)' \right\rangle - \left\langle \frac{1-y}{1-x}; \left(\frac{1-y}{1-x}\right)' \right\rangle + \left\langle \frac{x(1-y)}{y(1-x)}; \left(\frac{x(1-y)}{y(1-x)}\right)' \right\rangle$$

where $x, y \neq 0, 1$ and $x \neq y$ [4, 11].

2.8.2. *Tangent Complex to Bloch-Suslin Chain Complex for Weight 2.* Cathelineau [4] introduced following Tangent complex to Bloch-Suslin complex

$$T\mathcal{B}_2(F) \xrightarrow{\delta_\varepsilon} F \otimes F^\times \oplus \wedge^2 F^\times$$

where

$$\delta_\varepsilon : \langle x, y \rangle_2 = \left(\frac{y}{x} \otimes (1-x) + \frac{y}{(1-x)} \otimes x \right) + \left(\frac{y}{(1-x)} \wedge \frac{y}{x} \right)$$

see [4, 20].

2.8.3. *Tangent Complex to Goncharov Chain Complex for Weight 3.* Cathelineau [4] introduced following Tangent complex to Goncharov chain complex for weight 3

$$T\mathcal{B}_3(F) \xrightarrow{\delta_\varepsilon} (T\mathcal{B}_2(F) \otimes F^\times) \oplus (F \otimes \mathcal{B}_2(F)) \xrightarrow{\delta_\varepsilon} F \otimes \wedge^2 F^\times \oplus \wedge^3 F^\times$$

2.8.4. *Generalized Tangent Complex for any Tangent Group $T\mathcal{B}_n(F)$.* Cathelineau [4] generalized following Tangent complex to Goncharov chain complex for any weight n

$$T\mathcal{B}_n(F) \xrightarrow{\delta_{n,\varepsilon}} \begin{array}{c} T\mathcal{B}_{n-1}(F) \otimes F^\times \\ \oplus \\ F \otimes \mathcal{B}_{n-1}(F) \end{array} \xrightarrow{\delta_{(n-1),\varepsilon}} \dots \xrightarrow{\delta_{1,\varepsilon}} \begin{array}{c} T\mathcal{B}_2(F) \otimes \wedge^{n-2} F^\times \\ \oplus \\ F \otimes \mathcal{B}_2(F) \otimes \wedge^{n-3} F^\times \end{array} \xrightarrow{\delta_\varepsilon} (F \otimes \wedge^{n-1} F^\times) \oplus (\wedge^n F)$$

2.9. Geometry of Tangent and Configuration Chain Complexes up to Weight 3.

2.9.1. *Geometry for Weight 2.* As defined in [20], the geometry of Grassmannian configuration and Goncharov motivic in weight-2 is represented as

$$\begin{array}{ccccc} G_5(3) & \xrightarrow{p} & G_4(2) & \xrightarrow{g_{1,\varepsilon}^2} & T\mathcal{B}_2(F) \\ \downarrow d & & \downarrow d & & \downarrow \delta_\varepsilon \\ G_4(3) & \xrightarrow{p} & G_3(2) & \xrightarrow{g_{0,\varepsilon}^2} & F \otimes F^\times \oplus \wedge^2 F^\times \end{array} \quad (\text{C})$$

Lemma 2.10. *The diagram B is bi-complex and commutative [20].*

2.10.1. *Geometry for Weight 3.* The geometry of Grassmannian and Goncharov motivic for weight-3 is presented in [20] as follows:

$$\begin{array}{ccccc} G_7(3) & \xrightarrow{d} & G_6(3) & & \\ \downarrow p & & \downarrow p & & \\ G_6(2) & \xrightarrow{d} & G_5(2) & \xrightarrow{g_{1,\varepsilon}^3} & T\mathcal{B}_2(F) \otimes F^\times \oplus F \otimes \mathcal{B}_2(F) \\ \downarrow p & & \downarrow p & & \downarrow \delta_\varepsilon \\ G_5(1) & \xrightarrow{d} & G_4(1) & \xrightarrow{g_{0,\varepsilon}^3} & F \otimes \wedge^2 F^\times \oplus \wedge^3 F^\times \end{array} \quad (\text{D})$$

Lemma 2.11. *The diagram C is bi-complex and commutative [20].*

3. GEOMETRY OF TANGENT GROUPS AND CONFIGURATION CHAIN COMPLEXES FOR WEIGHT 4 & 5

3.1. **Geometry for Weight 4.** Geometry for weight 4 is defined as follows

$$\begin{array}{ccccc} G_7(\mathcal{A}_{F[\varepsilon],r}^5) & \xrightarrow{p} & G_6(\mathcal{A}_{F[\varepsilon]_2}^4) & \xrightarrow{g_{1,\varepsilon}^4} & T\mathcal{B}_2(F) \otimes \wedge^2 F^\times \oplus F \otimes \mathcal{B}_2(F) \otimes F^\times \\ \downarrow d & & \downarrow d & & \downarrow \delta_\varepsilon \\ G_6(\mathcal{A}_{F[\varepsilon],r}^5) & \xrightarrow{p} & G_5(\mathcal{A}_{F[\varepsilon]_2}^4) & \xrightarrow{g_{0,\varepsilon}^4} & F \otimes \wedge^3 F^\times \oplus \wedge^4 F^\times \end{array} \quad (\text{E})$$

where, $g_{0\varepsilon}^4(v_0^*, \dots, v_4^*) = g_{01}^4(v_0^*, \dots, v_4^*) + g_{02}^4(v_0^*, \dots, v_4^*)$

$$\begin{aligned} g_{01}^4(v_0^*, \dots, v_4^*) &= \sum_{i=j+1}^4 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_4^*)\varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_4)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)} \wedge \\ &\quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_4)} \quad (i \bmod 5), \end{aligned} \quad (3.10)$$

$$g_{02}^4(v_0^*, \dots, v_4^*) = \sum_{j=0}^4 (-1)^{j+1} \bigwedge_{\substack{j \neq i \\ j=0}}^4 \frac{\Delta(v_0^*, \dots, \hat{v}_j^*, \dots, v_4^*)\varepsilon}{\Delta(v_0, \dots, \hat{v}_j, \dots, v_4)} \quad (i \bmod 5) \quad (3.11)$$

and

$$\begin{aligned}
g_{1\varepsilon}^4(v_0^*, \dots, v_5^*) &= -\frac{1}{10} \sum_{i \neq j}^5 (-1)^i \left(\left\langle r(v_i, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \dots, v_5); r_\varepsilon(v_i^*, v_j^* | v_0^*, \dots, \hat{v}_i^*, \hat{v}_j^*, \dots, v_5^*) \right\rangle_2 \otimes \prod_{i \neq r}^5 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \dots, v_5) \wedge \right. \\
&\quad \left. \prod_{j \neq r}^5 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \dots, v_5) + \sum_{\substack{i \neq r \\ i=0}}^5 \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \hat{v}_r^*, \dots, v_5^*)_\varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \dots, v_5)} \otimes \right. \\
&\quad \left. [r(v_i, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \dots, v_5)]_2 \otimes \prod_{j \neq r}^5 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \dots, v_5) + \sum_{\substack{j \neq r \\ j=0}}^5 \frac{\Delta(v_0^*, \dots, \hat{v}_j^*, \hat{v}_r^*, \dots, v_5^*)_\varepsilon}{\Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \dots, v_5)} \otimes \right. \\
&\quad \left. [r(v_i, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \dots, v_5)]_2 \otimes \prod_{i \neq r}^5 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \dots, v_5) \right) \pmod{6}.
\end{aligned} \tag{3.12}$$

Lemma 3.2. *The right square of diagram E is commutative.*

$$\begin{array}{ccc}
G_6(\mathcal{A}_{F[\varepsilon]_2}^4) & \xrightarrow{d} & G_5(\mathcal{A}_{F[\varepsilon]_2}^4) \\
\downarrow g_{1,\varepsilon}^4 & & \downarrow g_{0,\varepsilon}^4 \\
T\mathcal{B}_2(F) \otimes F^\times \oplus F \otimes \mathcal{B}_2(F) \otimes F^\times & \xrightarrow{\delta_\varepsilon} & F \otimes \wedge^3 F^\times \oplus \wedge^4 F^\times
\end{array}$$

Proof. Let us assume $(v_0^*, \dots, v_5^*) \in G_6(\mathcal{A}_{F[\varepsilon]_2}^4)$ and apply morphism d

$$\begin{aligned}
d(v_0^*, \dots, v_5^*) &= \sum_{i=0}^5 (-1)^i (v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \\
&= (v_1^*, v_2^*, v_3^*, v_4^*, v_5^*) - (v_0^*, v_2^*, v_3^*, v_4^*, v_5^*) + (v_0^*, v_1^*, v_3^*, v_4^*, v_5^*) \\
&\quad - (v_0^*, v_1^*, v_2^*, v_4^*, v_5^*) + (v_0^*, v_1^*, v_2^*, v_3^*, v_5^*) - (v_0^*, v_1^*, v_2^*, v_3^*, v_4^*)
\end{aligned} \tag{3.13}$$

now first apply map g_{01}^4 , we get,

$$\begin{aligned}
g_{01}^4 \circ d(v_0^*, \dots, v_5^*) &= g_{01}^4(v_1^*, v_2^*, v_3^*, v_4^*, v_5^*) - g_{01}^4(v_0^*, v_2^*, v_3^*, v_4^*, v_5^*) + \\
&\quad g_{01}^4(v_0^*, v_1^*, v_3^*, v_4^*, v_5^*) - g_{01}^4(v_0^*, v_1^*, v_2^*, v_4^*, v_5^*) + \\
&\quad g_{01}^4(v_0^*, v_1^*, v_2^*, v_3^*, v_5^*) - g_{01}^4(v_0^*, v_1^*, v_2^*, v_3^*, v_4^*)
\end{aligned} \tag{3.14}$$

Expand by applying map g_{01}^4

$$g_{01}^4 \circ d(v_0^*, \dots, v_5^*) = \sum_{\substack{i \neq 0 \\ i=1}}^5 (-1)^{i+1} \frac{\Delta(v_1^*, \dots, \hat{v}_i^*, \dots, v_5^*)_\varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge$$

$$\begin{aligned}
 & \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 1 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 2 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 3 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 4 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 5 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)}. \tag{3.15}
 \end{aligned}$$

now compose map g_{02}^4 with $d(v_0^*, \dots, v_5^*)$, we get,

$$\begin{aligned}
 g_{02}^4 \circ d(v_0^*, \dots, v_5^*) &= g_{02}^4(v_1^*, v_2^*, v_3^*, v_4^*, v_5^*) - g_{02}^4(v_0^*, v_2^*, v_3^*, v_4^*, v_5^*) + \\
 & g_{02}^4(v_0^*, v_1^*, v_3^*, v_4^*, v_5^*) - g_{02}^4(v_0^*, v_1^*, v_2^*, v_4^*, v_5^*) + \\
 & g_{02}^4(v_0^*, v_1^*, v_2^*, v_3^*, v_5^*) - g_{02}^4(v_0^*, v_1^*, v_2^*, v_3^*, v_4^*) \tag{3.16}
 \end{aligned}$$

Expand by applying map g_{02}^4

$$\begin{aligned}
 g_{02}^4 \circ d(v_0^*, \dots, v_5^*) &= \sum_{\substack{i \neq 0 \\ i=1}}^5 (-1)^{i+1} \frac{\Delta(v_1^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} +
 \end{aligned}$$

$$\begin{aligned}
& \sum_{\substack{i \neq 1 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 2 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \quad \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 3 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 4 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^4 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_4^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_4)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_4)}.
\end{aligned} \tag{3.17}$$

Combine Eq.(3.15) and Eq.(3.17), then

$$\begin{aligned}
g_{0\varepsilon}^4 \circ d(v_0, \dots, v_4) &= \sum_{\substack{i \neq 0 \\ i=1}}^5 (-1)^{i+1} \frac{\Delta(v_1^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \quad \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 1 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} +
\end{aligned}$$

$$\begin{aligned}
 & \sum_{\substack{i \neq 2 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \quad \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 3 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 4 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 5 \\ i=0}}^4 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_4^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_4)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)} \wedge \\
 & \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_4)} + \\
 & \sum_{\substack{i \neq 0 \\ i=1}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 1 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 2 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
 & \quad \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
 & \sum_{\substack{i \neq 3 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge
 \end{aligned}$$

$$\begin{aligned}
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 4 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_{i+1}, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^4 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_{i+1}, \dots, v_4^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_4)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_4)}. \quad (3.18)
\end{aligned}$$

Take $(v_0^*, \dots, v_5^*) \in G_6(\mathcal{A}_{F[\varepsilon]}^4)$ again and apply morphism $g_{1\varepsilon}^4$

$$\begin{aligned}
g_{1\varepsilon}^4(v_0^*, \dots, v_5^*) &= -\frac{1}{10} \sum_{i \neq j}^5 (-1)^i \left(\left\langle r(v_i, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \dots, v_5); r_\varepsilon(v_i^*, v_j^* | v_0^*, \dots, \hat{v}_{i+1}, \hat{v}_{j+1}, \dots, v_5^*) \right\rangle_2 \otimes \right. \\
& \prod_{i \neq r}^5 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \dots, v_5) \wedge \prod_{j \neq r}^5 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \dots, v_5) + \\
& \sum_{\substack{i \neq r \\ i=0}}^5 \frac{\Delta(v_0^*, \dots, \hat{v}_{i+1}, \hat{v}_{r+1}, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \dots, v_5)} \otimes [r(v_i, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \dots, v_5)]_2 \otimes \\
& \prod_{j \neq r}^5 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \dots, v_5) + \sum_{\substack{j \neq r \\ j=0}}^5 \frac{\Delta(v_0^*, \dots, \hat{v}_{j+1}, \hat{v}_{r+1}, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \dots, v_5)} \otimes \\
& \left. [r(v_i, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \dots, v_5)]_2 \otimes \prod_{i \neq r}^5 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \dots, v_5) \right) \quad (3.19)
\end{aligned}$$

now apply morphism $\delta_{varepsilon}$, then

$$\begin{aligned}
\delta_\varepsilon \circ g_{1\varepsilon}^4(v_0^*, \dots, v_5^*) &= -\frac{1}{10} \sum_{i \neq j}^5 (-1)^i \left(\left\langle r(v_i, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \dots, v_5); r_\varepsilon(v_i^*, v_j^* | v_0^*, \dots, \hat{v}_{i+1}, \hat{v}_{j+1}, \dots, v_5^*) \right\rangle_2 \otimes \right. \\
& \prod_{i \neq r}^5 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \dots, v_5) \wedge \prod_{j \neq r}^5 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \dots, v_5) +
\end{aligned}$$

$$\begin{aligned}
& \sum_{\substack{i \neq r \\ i=0}}^5 \frac{\Delta(v_0^*, \dots, \hat{v}_i, \hat{v}_r^*, \dots, v_5^*)_\varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \dots, v_5)} \otimes [r(v_i, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \dots, v_5)]_2 \otimes \\
& \prod_{j \neq r}^5 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \dots, v_5) + \sum_{\substack{j \neq r \\ j=0}}^5 \frac{\Delta(v_0^*, \dots, \hat{v}_j, \hat{v}_r^*, \dots, v_5^*)_\varepsilon}{\Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \dots, v_5)} \otimes \\
& [r(v_i, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \dots, v_5)]_2 \otimes \prod_{i \neq r}^5 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \dots, v_5).
\end{aligned} \tag{3.20}$$

Using wedge and Siegel cross ratio properties [21], then above Eq.(3.20) becomes

$$\begin{aligned}
\delta_\varepsilon \circ g_{1\varepsilon}^4(v_0^*, \dots, v_5^*) &= \sum_{\substack{i \neq 0 \\ i=1}}^5 (-1)^{i+1} \frac{\Delta(v_1^*, \dots, \hat{v}_i, \dots, v_5^*)_\varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 1 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i, \dots, v_5^*)_\varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 2 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i, \dots, v_5^*)_\varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 3 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i, \dots, v_5^*)_\varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 4 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i, \dots, v_5^*)_\varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^4 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i, \dots, v_4^*)_\varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_4)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)} \wedge
\end{aligned}$$

$$\begin{aligned}
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_4)} + \\
& \sum_{\substack{i \neq 0 \\ i=1}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 1 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 2 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 3 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 4 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^4 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_4^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_4)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_4)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_4)}.
\end{aligned} \tag{3.21}$$

So from Eq.(3.15) and Eq.(3.21), it is proved that the above diagram is commutative. \square

3.3. Geometry for Weight 5. For weight 5 we have following commutative diagram

$$\begin{array}{ccccc}
G_8(\mathcal{A}_{F[\varepsilon]_2}^6) & \xrightarrow{p} & G_7(\mathcal{A}_{F[\varepsilon]_2}^5) & \xrightarrow{g_{1,\varepsilon}^5} & T\mathcal{B}_2(F) \otimes \wedge^3 F^\times \oplus F \otimes \mathcal{B}_2(F) \otimes \wedge^2 F^\times & (F) \\
\downarrow d & & \downarrow d & & \downarrow \delta_\varepsilon \\
G_7(\mathcal{A}_{F[\varepsilon]_2}^6) & \xrightarrow{p} & G_6(\mathcal{A}_{F[\varepsilon]_2}^5) & \xrightarrow{g_{0,\varepsilon}^5} & F \otimes \wedge^4 F^\times \oplus \wedge^5 F^\times
\end{array}$$

where, $g_{0\varepsilon}^5(v_0^*, \dots, v_5^*) = g_{01}^5(v_0^*, \dots, v_5^*) + g_{02}^5(v_0^*, \dots, v_5^*)$

$$\begin{aligned}
g_{01}^5(v_0^*, \dots, v_5^*) &= \sum_{i=j+1}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*)\varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
&\quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} \wedge \\
&\quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_5)} (i \bmod 6), & (3.22)
\end{aligned}$$

$$g_{02}^5(v_0^*, \dots, v_5^*) = \sum_{j=0}^5 (-1)^{j+1} \bigwedge_{\substack{j \neq i \\ j=0}}^5 \frac{\Delta(v_0^*, \dots, \hat{v}_j^*, \dots, v_5^*)\varepsilon}{\Delta(v_0, \dots, \hat{v}_j, \dots, v_5)} (i \bmod 6) \quad (3.23)$$

and

$$\begin{aligned}
g_{1\varepsilon}^5(v_0^*, \dots, v_6^*) &= \frac{1}{15} \sum_{i \neq j}^6 (-1)^i \left(\left\langle r(v_i, v_j, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \hat{v}_k, \dots, v_6); r_\varepsilon(v_i^*, v_j^*, v_k^* | v_0^*, \dots, \right. \right. \\
&\quad \left. \left. \hat{v}_i^*, \hat{v}_j^*, \hat{v}_k^*, \dots, v_6^*) \right\rangle_2 \otimes \prod_{i \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \right. \\
&\quad \prod_{j \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{k \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, v_6) \\
&\quad \left. + \sum_{\substack{i \neq r \neq s \\ i=0}}^6 \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \hat{v}_r^*, \hat{v}_s^*, \dots, v_6^*)\varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \dots, v_6)} \otimes [r(v_i, v_j, v_k | v_0, \dots, \hat{v}_i, \hat{v}_j, \hat{v}_k, \right. \\
&\quad \left. \dots, v_6)]_2 \otimes \prod_{j \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{k \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \right. \\
&\quad \left. \dots, v_6) + \sum_{\substack{j \neq r \neq s \\ j=0}}^6 \frac{\Delta(v_0^*, \dots, \hat{v}_j^*, \hat{v}_r^*, \hat{v}_s^*, \dots, v_6^*)\varepsilon}{\Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6)} \otimes [r(v_i, v_j, v_k | v_0, \dots, \hat{v}_i, \right. \\
&\quad \left. \hat{v}_j, \hat{v}_k, \dots, v_6)]_2 \otimes \prod_{k \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{i \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_i, \right.
\end{aligned}$$

$$\begin{aligned}
& \hat{v}_r, \hat{v}_s, \dots, v_6) + \sum_{\substack{k \neq r \neq s \\ k=0}}^6 \frac{\Delta(v_0^*, \dots, \hat{v}_k^*, \hat{v}_r^*, \hat{v}_s^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, v_6)} \otimes [r(v_i, v_j, v_k | v_0, \\
& \dots, \hat{v}_i, \hat{v}_j, \hat{v}_k, \dots, v_6)]_2 \otimes \prod_{i \neq r \neq s}^5 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{j \neq r \neq s}^6 \Delta(v_0, \\
& \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6) \pmod{6}. \tag{3.24}
\end{aligned}$$

Lemma 3.4. *The right square of diagram F is commutative.*

$$\begin{array}{ccc}
G_7(\mathcal{A}_{F[\varepsilon]_2}^5) & \xrightarrow{g_{1,\varepsilon}^5} & T\mathcal{B}_2(F) \otimes \wedge^3 F^\times \oplus F \otimes \mathcal{B}_2(F) \otimes \wedge^2 F^\times \\
\downarrow d & & \downarrow \delta_\varepsilon \\
G_6(\mathcal{A}_{F[\varepsilon]_2}^5) & \xrightarrow{g_{0,\varepsilon}^5} & F \otimes \wedge^4 F^\times \oplus \wedge^5 F^\times
\end{array}$$

Proof. Let us assume $(v_0^*, \dots, v_6^*) \in G_7(\mathcal{A}_{F[\varepsilon]_2}^5)$ and apply morphism d

$$d(v_0^*, \dots, v_6^*) = \sum_{i=0}^6 (-1)^j (v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*)$$

\Rightarrow

$$\begin{aligned}
d(v_0^*, \dots, v_6^*) &= (v_1^*, v_2^*, v_3^*, v_4^*, v_5^*, v_6^*) - (v_0^*, v_2^*, v_3^*, v_4^*, v_5^*, v_6^*) + \\
& (v_0^*, v_1^*, v_3^*, v_4^*, v_5^*, v_6^*) - (v_0^*, v_1^*, v_2^*, v_4^*, v_5^*, v_6^*) + \\
& (v_0^*, v_1^*, v_2^*, v_3^*, v_5^*, v_6^*) - (v_0^*, v_1^*, v_2^*, v_3^*, v_4^*, v_6^*) + \\
& (v_0^*, v_1^*, v_2^*, v_3^*, v_4^*, v_5^*) \tag{3.25}
\end{aligned}$$

now first apply map g_{01}^5 , we get,

$$\begin{aligned}
g_{01}^5 \circ d(v_0^*, \dots, v_6^*) &= g_{01}^5(v_1^*, v_2^*, v_3^*, v_4^*, v_5^*, v_6^*) - g_{01}^5(v_0^*, v_2^*, v_3^*, v_4^*, v_5^*, v_6^*) + \\
& g_{01}^5(v_0^*, v_1^*, v_3^*, v_4^*, v_5^*, v_6^*) - g_{01}^5(v_0^*, v_1^*, v_2^*, v_4^*, v_5^*, v_6^*) + \\
& g_{01}^5(v_0^*, v_1^*, v_2^*, v_3^*, v_5^*, v_6^*) - g_{01}^5(v_0^*, v_1^*, v_2^*, v_3^*, v_4^*, v_6^*) + \\
& g_{01}^5(v_0^*, v_1^*, v_2^*, v_3^*, v_4^*, v_5^*) \tag{3.26}
\end{aligned}$$

Expand by applying map g_{01}^5

$$\begin{aligned}
g_{01}^5 \circ d(v_0^*, \dots, v_6^*) &= \sum_{\substack{i \neq 0 \\ i=1}}^6 (-1)^{i+1} \frac{\Delta(v_1^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+5}, \dots, v_6)} +
\end{aligned}$$

$$\begin{aligned}
& \sum_{\substack{i \neq 1 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 2 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 3 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 4 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 6 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge
\end{aligned}$$

$$\frac{\frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)}}{\frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_5)}} \quad (3.27)$$

now compose map g_{02}^5 with $d(v_0^*, \dots, v_6^*)$, we get,

$$\begin{aligned} g_{02}^5 \circ d(v_0^*, \dots, v_6^*) &= g_{02}^5(v_1^*, v_2^*, v_3^*, v_4^*, v_5^*, v_6^*) - g_{02}^5(v_0^*, v_2^*, v_3^*, v_4^*, v_5^*, v_6^*) + \\ &g_{02}^5(v_0^*, v_1^*, v_3^*, v_4^*, v_5^*, v_6^*) - g_{02}^5(v_0^*, v_1^*, v_2^*, v_4^*, v_5^*, v_6^*) + \\ &g_{02}^5(v_0^*, v_1^*, v_2^*, v_3^*, v_5^*, v_6^*) - g_{02}^5(v_0^*, v_1^*, v_2^*, v_3^*, v_4^*, v_5^*). \end{aligned} \quad (3.28)$$

Expand by applying map g_{02}^5

$$\begin{aligned} g_{02}^5 \circ d(v_0^*, \dots, v_6^*) &= \sum_{\substack{i \neq 0 \\ i=1}}^6 (-1)^{i+1} \frac{\Delta(v_1^*, \dots, \hat{v}_i, \dots, v_6^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\ &\frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\ &\frac{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\ &\sum_{\substack{i \neq 1 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\ &\frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\ &\frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\ &\sum_{\substack{i \neq 2 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\ &\frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\ &\frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\ &\sum_{\substack{i \neq 3 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\ &\frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\ &\frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \end{aligned}$$

$$\begin{aligned}
& \sum_{\substack{i \neq 4 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 6 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_5)}. \tag{3.29}
\end{aligned}$$

Add Eq.(3.27) and Eq.(3.29), then,

$$\begin{aligned}
g_{0,\varepsilon}^5 \circ d(v_0^*, \dots, v_6^*) &= \sum_{\substack{i \neq 0 \\ i=1}}^6 (-1)^{i+1} \frac{\Delta(v_1^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 1 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 2 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge
\end{aligned}$$

$$\begin{aligned}
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 3 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 4 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_5)} + \\
& \sum_{\substack{i \neq 0 \\ i=1}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} +
\end{aligned}$$

$$\frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_5)}. \quad (3.30)$$

Take $(v_0^*, \dots, v_6^*) \in G_7(\mathcal{A}_{F[\varepsilon]_r}^5)$ again and compose with morphism $g_{1,\varepsilon}^5$, then

$$\begin{aligned} g_{1,\varepsilon}^5(v_0^*, \dots, v_6^*) &= \frac{1}{15} \sum_{i \neq j}^6 (-1)^i \left(\left\langle r(v_i, v_j, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \hat{v}_k, \dots, v_6); r_\varepsilon(v_i^*, v_j^*, v_k^* | v_0^*, \dots, \hat{v}_i^*, \hat{v}_j^*, \hat{v}_k^*, \dots, v_6^*) \right\rangle_2 \otimes \prod_{i \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \right. \\ &\quad \prod_{j \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{k \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, v_6) + \\ &\quad \sum_{\substack{i \neq r \neq s \\ i=0}}^6 \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \hat{v}_r^*, \hat{v}_s^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \dots, v_6)} \otimes [r(v_i, v_j, v_k | v_0, \dots, \hat{v}_i, \hat{v}_j, \hat{v}_k, \dots, \\ &\quad v_6)]_2 \otimes \prod_{j \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{k \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, \\ &\quad v_6) + \sum_{\substack{j \neq r \neq s \\ j=0}}^6 \frac{\Delta(v_0^*, \dots, \hat{v}_j^*, \hat{v}_r^*, \hat{v}_s^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6)} \otimes [r(v_i, v_j, v_k | v_0, \dots, \hat{v}_i, \hat{v}_j, \\ &\quad \hat{v}_k, \dots, v_6)]_2 \otimes \prod_{k \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{i \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \\ &\quad \hat{v}_s, \dots, v_6) + \sum_{\substack{k \neq r \neq s \\ k=0}}^6 \frac{\Delta(v_0^*, \dots, \hat{v}_k^*, \hat{v}_r^*, \hat{v}_s^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, v_6)} \otimes [r(v_i, v_j, v_k | v_0, \dots, \\ &\quad \hat{v}_i, \hat{v}_j, \hat{v}_k, \dots, v_6)]_2 \otimes \prod_{i \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{j \neq r \neq s}^6 \Delta(v_0, \dots, \\ &\quad \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6) \end{aligned} \quad (3.31)$$

now apply morphism δ_ε , then

$$\begin{aligned} \delta_\varepsilon \circ g_{1,\varepsilon}^5(v_0^*, \dots, v_6^*) &= \frac{1}{15} \sum_{i \neq j}^6 (-1)^i \left(\left\langle r(v_i, v_j, v_j | v_0, \dots, \hat{v}_i, \hat{v}_j, \hat{v}_k, \dots, v_6); r_\varepsilon(v_i^*, v_j^*, \right. \right. \\ &\quad \left. \left. v_k^* | v_0^*, \dots, \hat{v}_i^*, \hat{v}_j^*, \hat{v}_k^*, \dots, v_6^*) \right\rangle_2 \otimes \prod_{i \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \dots, \right. \end{aligned}$$

$$\begin{aligned}
 & v_6) \wedge \prod_{j \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{k \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \\
 & \hat{v}_s, \dots, v_6) + \sum_{\substack{i \neq r \neq s \\ i=0}}^6 \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \hat{v}_r^*, \hat{v}_s^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \dots, v_6)} \otimes [r(v_i, v_j, \\
 & v_k | v_0, \dots, \hat{v}_i, \hat{v}_j, \hat{v}_k, \dots, v_6)]_2 \otimes \prod_{j \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \\
 & \prod_{k \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, v_6) + \\
 & \sum_{\substack{j \neq r \neq s \\ j=0}}^6 \frac{\Delta(v_0^*, \dots, \hat{v}_j^*, \hat{v}_r^*, \hat{v}_s^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6)} \otimes [r(v_i, v_j, v_k | v_0, \dots, \hat{v}_i, \\
 & \hat{v}_j, \hat{v}_k, \dots, v_6)]_2 \otimes \prod_{k \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, v_6) \wedge \prod_{i \neq r \neq s}^6 \Delta(v_0, \\
 & \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \dots, v_6) + \sum_{\substack{k \neq r \neq s \\ k=0}}^6 \frac{\Delta(v_0^*, \dots, \hat{v}_k^*, \hat{v}_r^*, \hat{v}_s^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_k, \hat{v}_r, \hat{v}_s, \dots, v_6)} \otimes \\
 & [r(v_i, v_j, v_k | v_0, \dots, \hat{v}_i, \hat{v}_j, \hat{v}_k, \dots, v_6)]_2 \otimes \prod_{i \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_i, \hat{v}_r, \hat{v}_s, \\
 & \dots, v_6) \wedge \prod_{j \neq r \neq s}^6 \Delta(v_0, \dots, \hat{v}_j, \hat{v}_r, \hat{v}_s, \dots, v_6) \tag{3.32}
 \end{aligned}$$

Using wedge and Siegel cross ratio properties [21], then above Eq.(3.32) becomes

$$\begin{aligned}
 \delta_\varepsilon \circ g_{1,\varepsilon}^5(v_0^*, \dots, v_6^*) &= \sum_{\substack{i \neq 0 \\ i=1}}^6 (-1)^{i+1} \frac{\Delta(v_1^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
 & \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
 & \frac{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
 & \sum_{\substack{i \neq 1 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
 & \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge
 \end{aligned}$$

$$\begin{aligned}
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i=0 \\ i \neq 2}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_{i+1}^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i=0 \\ i \neq 3}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_{i+1}^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i=0 \\ i \neq 4}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_{i+1}^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i=0 \\ i \neq 5}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_{i+1}^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i=0 \\ i \neq 5}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_{i+1}^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \otimes \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_5)} +
\end{aligned}$$

$$\begin{aligned}
& \sum_{\substack{i \neq 0 \\ i=1}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_1, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_1, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_1, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_1, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 1 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 2 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 3 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 4 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \quad \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^6 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_6^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)} \wedge
\end{aligned}$$

$$\begin{aligned}
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_6)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_6)} + \\
& \sum_{\substack{i \neq 5 \\ i=0}}^5 (-1)^{i+1} \frac{\Delta(v_0^*, \dots, \hat{v}_i^*, \dots, v_5^*) \varepsilon}{\Delta(v_0, \dots, \hat{v}_i, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+1}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+2}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)} \wedge \frac{\Delta(v_0, \dots, \hat{v}_{i+3}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)} \wedge \\
& \frac{\Delta(v_0, \dots, \hat{v}_{i+4}, \dots, v_5)}{\Delta(v_0, \dots, \hat{v}_{i+5}, \dots, v_5)}. \tag{3.33}
\end{aligned}$$

□

From Eq.(3.30) and Eq.(3.33), it can be seen that the map of morphism between the tangential and configuration chain complex for weight 5 is commutative.

4. CONCLUSION

In this research work, new morphisms have been presented for 4 and 5 dimensional affine space to define the geometry between tangential and configuration chain complexes. The composite maps for weight 4 and 5 are found to be commutative. In a similar technique, the tangential group $T\mathcal{B}_n(F)$ for any weight “n” can be defined by relating them with suitable complex.

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